Probability and Statistical Decision Theory

Volume A

Edited by

F. Konecny,

J. Mogyoródi, and

W. Wertz

PROBABILITY AND STATISTICAL DECISION THEORY

Proceedings of the 4th Pannonian Symposium on Mathematical Statistics,
Bad Tatzmannsdorf, Austria, 4–10 September, 1983

Volume A

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The Fourth Pannonian Symposium on Mathematical Statistics was held in Bad Tatzmannsdorf, Austria, 4-10 September, 1983. The first two Symposia were held there in 1979 and 1981, whereas the Third Symposium was staged in Visegrád, Hungary in 1982. The proceedings volumes of these conferences, published by Springer, D. Reidel, and D. Reidel & Akadémiai Kiadó, respectively, give information about the objective of the Pannonian Symposia and the topics covered.

About 130 participants from 17 countries took part in this Fourth Symposium, and 92 lectures were presented. This volume contains 24 reviewed contributions which are mainly mathematically oriented. A second group of papers dealing with problems of applied statistics, probability theory and related topics is published in a separate volume entitled "Mathematical Statistics and Applications".

The contributions dealing with probability theory concentrate on two (intersecting) main topics: on the one hand, stochastic processes, and, on the other hand, limit theorems and invariance principles: Gaussian Processes, approximation of the Wiener Process, distribution of spacings and of order statistics, limit theorems in triangular arrays. Besides, adjacent topics like erdogic theory, maximal inequalities, approximation of convolutions of distribution functions, stochastic programming etc. are dealt with. In many of these contributions stress is laid upon the weakening of the assumption of independence.

The subjects of the statistical contributions are even more homogeneous: there are decision-theoretic papers (treating

admissibility, sufficiency, limits of experiments, etc.) and papers on nonparametric estimation (nonparametric estimators of regression curves, further rank-, L- and shrinkage estimators). One paper gives a comprehensive survey of two-sided parametric tests.

The reader will observe at once the close connections between many of the questions under consideration; in particular, many results of papers which can be related to probability theory have immediate applications in statistics, and some belong to the common boundary of these subjects.

We wish to express our thanks to many persons who gave us indispensable aid in the edition of this volume: S. Csörgő,
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The organization of the Symposium was made possible by the help of many individuals and institutions. The organizers gratefully acknowledge the generous support given by the State Government of Burgenland, the Federal Ministry of Science and Research, the Austrian Statistical Society, the Control Data Co., Hypobank of Burgenland Co., the Volksbank Oberwart Co., the Raiffeisenbank Oberwart Co., the Kurbad Tatzmannsdorf Co. and the Local Autority of Bad Tatzmannsdorf; special thanks go to Th. Kery and Dr. R. Grohotolsky (Head and Vice-Head of Burgenland resp.), Dr. J. Karall (Member of the State Government of Burgenland). DDr. Schranz (Member of State Parliament of Burgenland) and Mag. R. Luipersbeck (Director of the Kurbad Tatzmannsdorf AG) for their help in many respects. Finally, we express

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Wolfgang WEF:

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DISTRIBUTION FREE EXPONENTIAL BOUND FOR THE L1ERROR OF PARTITIONING-ESTIMATES OF A REGRESSION FUNCTION

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ABSTRACT

Let $m_n(x)$ be a partitioning estimate of a regression function $m(x) = \mathbb{E}(Y/X=x)$ for the sample (X_1,Y_1) ... (X_n,Y_n) . If $|Y| \leq K < \infty$ a.s. and μ denotes the probability measure of X then, under some mild conditions on the sequence of partitions, for each $\varepsilon > 0$ there exists an n_0 such that

$$\mathbb{P}(\int |\mathbf{m}_{n}(\mathbf{x}) - \mathbf{m}(\mathbf{x}) | \mu(d\mathbf{x}) > \varepsilon) \leq \exp(-c(\varepsilon/K)^{2}n)$$

for every n>n0 where c is a universal constant.

INTRODUCTION

Let (X,Y) (X_1,Y_1) , ... (X_n,Y_n) be independent identically distributed $\mathbb{R}^d x [-K,K]$ valued random vectors, and let m(x) = E(Y/X=x) be the regression function of Y on X, to be estimated from the data $D_n = \{(X_1,Y_1), \ldots, (X_n,Y_n)\}$.

Let μ , μ be the probability measures of X and (X,Y), μ_n and μ_n be the empirical probability measure for X_1 , X_2 ,... X_n and (X_1,Y_1) ,... (X_n,Y_n) , respectively. The signed measures ν_n (A) and ν (A) are defined by

$$v_n(A) = \frac{1}{n} \sum_{i=1}^{n} I_{X_i \in A} \longrightarrow Y_i$$

$$v(A) = \mathbb{E}v_n(A)$$
.

 $v(A) = Ev_n(A)$.

for every Borel set A.

A partitioning estimate is based on a finite or countable infinite Borel measurable partition \mathcal{P}_n of $\mathbb{R}^d(\mathcal{F}_n = \{A_{n_1}, A_{n_2}, \ldots\})$. If $A_n(x)$ is the set from \mathcal{G}_n to which x belongs, then the estimate is given by

$$m_{n}(x) = \begin{cases} \frac{v_{n}(A_{n}(x))}{\mu_{n}(A_{n}(x))}, & \text{if } v_{n}(A_{n}(x)) > 0 \\ \frac{1}{n}\sum_{i=1}^{n} Y_{i}, & \text{otherwise.} \end{cases}$$
 (2)

It is called fixed, if \mathcal{G}_n does not depend upon the data, and variable, if \mathfrak{F}_n depends upon the data (for measurability reasons, in latter case, we have to assume the membership function mapping x and D_n to {1,2, ...} to be Borel measurable). Fixed partitioning estimates are also called histogram estimates.

A sequence of estimates is said to be cubic if there exist positive numbers $a_1, \ldots a_d$ such that each \mathcal{P}_n consists entirely of sets of the form $\prod_{i=1}^{n} [a_i j_i h_n, a_i (j_i+1) h_n)$ where $j_1, \ldots j_d$ are integers and $\{h_n\}$ is a sequence of positive numbers.

Cubic sequences are particularly attractive from the computational point of view, because the set $A_n(x)$ can be determined for each x in constant time, independent of the data size n. This property is not shared by other sequences: for example, if all the A_{ni} 's are rectangles of different proportions, the membership determination can be done in time bounded from below by logn provided that a binary tree is created for locating an interval. In most cases, partitioning estimates are computationally superior to the other nonparametric estimates, particularly if the search for $A_n(x)$ is organized using binary decision trees (see for example, Friedman (1977)).

In this note we study only the fixed partitioning. The weak universal consistency of variable partitioning estimate was established by Gordon and Olshen (1980).

MAIN RESULT

Theorem If for each sphere S centered at the origin

$$\lim_{n\to\infty} \frac{1}{n} \sum_{i:A_{ni} \cap S \neq \emptyset} 1 = 0$$
(3)

and

$$\lim_{n\to\infty} \max_{\mathbf{i}; \mathbf{A}_{ni}} \{\sup_{\mathbf{x}, \mathbf{y}\in \mathbf{A}_{ni}} ||\mathbf{x}-\mathbf{y}||\} = 0$$

$$\mathbf{x}, \mathbf{y}\in \mathbf{A}_{ni}$$
(4)

then for the partitioning estimate (2) and for each $\epsilon\!>\!0$ there exists n such that

$$\mathbb{P}(f|m_n(x) - m(x)|\mu(dx) \ge \varepsilon) < \exp(-c(\varepsilon/K)^2 n) \qquad n \ge n$$

where c is universal (for example c=1/400).

Remark 1 If Υ_n is a cubic sequence of partitions then the conditions (3) and (4) are equivalent to

$$\lim_{n\to\infty} h_n = 0, \quad \lim_{n\to\infty} nh_n^{d} = \infty$$
(6)

Applying Stone's Theorem (Stone, 1977) it is easy to check that for cubic partitions (6) is necessary and sufficient condition for

$$\lim_{n\to\infty} \mathbb{E}(f|m_n(x) - m(x)|\mu(dx)|) = 0$$

for all distributions of (X,Y) to hold.

Remark 2 One of the most important consequences of this theorem is the exponential rate of convergence of the error probability in discrimination. If $X, X_1, \ldots X_n$ are as before, $Y, Y_1, \ldots Y_n$ take values in $\{1, 2, \ldots M\}$ and the task of the discrimination is to decide on Y given X and D_n , then partitioning rule is defined as follows:

$$g_{n}(X) = i \quad \text{if} \quad \sum_{j=1}^{n} I \left[X_{j} \in A_{n}(X), Y_{j} = i \right] = \max_{\ell} \sum_{j=1}^{n} I \left[X_{j} \in A_{n}(X), Y_{j} = \ell \right].$$

If L* denotes the (optimal) Bayesian error probability and

$$L_n = \mathbb{P}(g_n(X) \neq Y | D_n),$$

then our Theorem implies that for each $\varepsilon>0$

$$\mathbb{P}(L_n - L^* > \varepsilon) \leq \exp(-c\varepsilon^2 n) \qquad n \geq n_0.$$

The proof of this bound is based on the well known relation of $L_n - L^*$ and the L_1 errors of aposteriori probability estimates (see, for example Devroye(1982)).

PROOFS

For a sphere S put

$$I_{Sn} = \{i; A_{ni} \cap S \neq \emptyset\}$$

Lemma 1 If $|I_{Sn}|/n < (\varepsilon/K)^2/20$ then

$$\mathbf{P}(\mathbf{K} \sum_{\mathbf{i} \in \mathbf{I}_{Sn}} |\mu_{\mathbf{n}}(\mathbf{A}_{\mathbf{n}i}) - \mu(\mathbf{A}_{\mathbf{n}i})| > \varepsilon) \le 3 \exp(-\frac{1}{25}(\varepsilon/K)^{2}n)$$
 (7)

and if $|I_{Sn}|/n < (\epsilon/K)^3/2160$ then.

$$\mathbf{P} \left(\sum_{\mathbf{n}} | \mathbf{v}_{\mathbf{n}}(\mathbf{A}_{\mathbf{n}i}) - \mathbf{v}(\mathbf{A}_{\mathbf{n}i}) | > \varepsilon \right) \leq 3 \exp \left(-\frac{1}{26} (\varepsilon/K)^2 \mathbf{n} \right)$$

$$i \in \mathbf{I}_{\mathbf{S}\mathbf{n}}$$
(8)

Proof (7) was proved in Devroye (1983, Lemma 3). (8) is a
consequence of (7). To proving this, for a fixed integer N
put

$$D_{i} = \left[i\frac{\varepsilon}{N}, (i+1)\frac{\varepsilon}{N}\right],$$

and

$$c_i = \frac{2i+1}{2} \frac{\varepsilon}{N}, \qquad (-\frac{K}{\varepsilon/N} \le i \le \frac{K}{\varepsilon/N}),$$

and

$$\tilde{Y}_{j} = \sum_{i} c_{i} I_{D_{i}}(Y_{j})$$

then Y_j is a quantized version of Y_j with step size ϵ/N , therefore

$$|\tilde{Y}_{j} - Y_{j}| < \frac{\varepsilon}{2N}$$

and if $\tilde{\nu}_n$, $\tilde{\nu}$ stand for ν_n , ν , resp., when $\{Y_j\}$ is replaced by $\{\tilde{Y}_j\}$ then

$$\sum_{i} |\tilde{v}_{n}(A_{ni}) - v_{n}(A_{ni})| < \frac{\varepsilon}{2N}$$

and

$$\sum_{i} \tilde{v}(A_{ni}) - v(A_{ni}) | < \frac{\varepsilon}{2N}$$

Thus

$$\frac{\mathbb{P}(\Sigma_{i \in I_{Sn}} | \nu_n(A_{ni}) - \nu(A_{ni}) | > \epsilon) <$$

$$< \mathbb{IP} \left(\sum_{i \in I_{Sn}} | \widetilde{v}_{n}(A_{ni}) - \widetilde{v}(A_{ni}) | > \varepsilon - \frac{\varepsilon}{N} \right) =$$

$$= \mathbb{P}\left(\sum_{i \in I_{Sn}} \left| \sum_{i'} \frac{1}{n} \sum_{j=1}^{n} c_{i'} (I_{X_{j}} \epsilon A_{ni}, Y_{j} \epsilon D_{i'}) - \mathbb{E}\left(I_{X_{j}} \epsilon A_{ni}, Y_{j} \epsilon D_{ii'}\right)\right)\right|$$

$$\left(> \epsilon \left(1 - \frac{1}{N}\right)\right) <$$

$$< \mathbb{P}(K \sum_{i \in I_{Sn}} \sum_{i'} | \frac{1}{n} \sum_{j=1}^{n} I [X_j \in A_{ni}, Y_j \in D_{i'}] - \mathbb{E}(I [X_i \in A_{ni}, Y_i \in D_{i'}]) | >$$

$$> \varepsilon (1 - \frac{1}{N})) =$$

$$= \mathbb{IP} \left(K \sum_{\mathbf{i} \in \mathbf{I}_{Sn}} \sum_{\mathbf{i'}} | \tilde{\mu}_{n}(A_{n\mathbf{i}}, D_{\mathbf{i'}}) - \tilde{\mu}(A_{n\mathbf{i}}, D_{\mathbf{i'}}) | > \varepsilon (1 - \frac{1}{N}) \right)$$

Applying (7) for N=52 and for the measure μ we get (8). Lemma 2 Under the condition (4), for each sphere S

$$\lim_{n\to\infty} \sum_{\mathbf{i}\in\mathbf{I}} \int_{\mathbf{S}n} \frac{\nabla (\mathbf{A}_{n\mathbf{i}})}{\mathbf{A}_{n\mathbf{i}}} - m(\mathbf{x}) | \mu(d\mathbf{x}) = 0$$
 (9)

Proof

$$\frac{v(A)}{\mu(A)} = \frac{\int_{A}^{b} m(z) \mu(dz)}{\mu(A)}$$

therefore if m is uniformly continuous then (4) implies (9).

For a given $\varepsilon>0$ and for an arbitrary m choose a uniformly continuous functionuous function m such that

$$f \mid m(z) - m(z) \mid \mu(dz) < \epsilon$$

then

$$\sum_{\mathbf{i} \in \mathbf{I}_{Sn}} \int_{\mathbf{A}_{ni}} \left| \frac{v(\mathbf{A}_{ni})}{\mu(\mathbf{A}_{ni})} - m(\mathbf{x}) \right| \mu(d\mathbf{x}) <$$

$$\leq \sum_{\mathbf{i} \in \mathbf{I}_{Sn^*}} \int_{\mathbf{A}_{ni}} \left| \frac{\mathbf{A}_{ni}^{\mathbf{m}(z)\mu(dz)}}{\mathbf{A}_{ni}} - \frac{\mathbf{A}_{ni}^{\mathbf{m}(z)\mu(dz)}}{\mathbf{A}_{ni}} \right| \mu(dx) +$$

$$+\sum_{\mathbf{i}\in\mathbf{I}_{Sn}}\int_{\mathbf{A}_{\mathbf{n}\mathbf{i}}}\left|\frac{\int_{\mathbf{A}_{\mathbf{n}\mathbf{i}}}\tilde{\mathbf{m}}(\mathbf{z})\mu(d\mathbf{z})}{\frac{\mathbf{A}_{\mathbf{n}\mathbf{i}}}{\mu(\mathbf{A}_{\mathbf{n}\mathbf{i}})}}-\tilde{\mathbf{m}}(\mathbf{x})\right|\mu(d\mathbf{x})+$$

+
$$\sum_{i \in I_{Sn}} \int_{A_{ni}} | \tilde{m}(x) - \tilde{m}(x) | \mu(dx) \le$$

$$\leq 2\varepsilon + \sum_{\mathbf{i} \in \mathbf{I}_{Sn}} \int_{\mathbf{A}_{ni}} \frac{A_{ni}}{\mu(\mathbf{A}_{ni})} - \tilde{m}(\mathbf{x}) | \mu(d\mathbf{x});$$

by the first part of the roof, Lemma 2 follows.

Proof of the Theorem For an arbitrary sphere S

$$f|m_n(x) - m(x)| \mu(dx) \le$$

$$\leq 2K \mu(S^{c}) + \sum_{\substack{i \\ A_{ni} \land S \neq \emptyset}} \int_{\mathbf{n}i} |\mathbf{m}_{n}(\mathbf{x}) - \mathbf{m}(\mathbf{x})| \mu(d\mathbf{x})$$

$$A_{ni} \land S \neq \emptyset$$

$$\mu(A_{ni}) > 0$$

$$(10)$$

For $\mu(A_{ni}) > 0$ we have

$$\int |m_{n}(x) - m(x)| \mu(dx) \le A_{ni}$$

$$\leq \int_{\mathbf{A_{ni}}} |\mathbf{m_{n}(x)} - \frac{v_{n}(\mathbf{A_{ni}})}{\mu(\mathbf{A_{ni}})}| \mu(\mathbf{dx}) + |\frac{v_{n}(\mathbf{A_{ni}})}{\mu(\mathbf{A_{ni}})} - \frac{v(\mathbf{A_{ni}})}{\mu(\mathbf{A_{ni}})}| \mu(\mathbf{A_{ni}}) + \int_{\mathbf{A_{ni}}} |\frac{v(\mathbf{A_{ni}})}{\mu(\mathbf{A_{ni}})} - \mathbf{m(x)}| \mu(\mathbf{dx})$$

$$\leq \int_{\mathbf{A_{ni}}} |\mathbf{m_{n}(x)} - \frac{v(\mathbf{A_{ni}})}{\mu(\mathbf{A_{ni}})} - \frac{v(\mathbf{A_{ni}})}{\mu(\mathbf{A_{ni}})} + \frac{v(\mathbf{A_{ni}})}{\mu(\mathbf{A_{ni}})}$$

If $\mu(\mathbf{A}_{ni})>0$ and $\mu_n(\mathbf{A}_{ni})>0$ then

$$\int_{A_{ni}} (m_n(x) - \frac{v_n(A_{ni})}{\mu(A_{ni})} | \mu(dx) =$$

$$= \left| \frac{\nu_{\mathbf{n}}(\mathbf{A}_{\mathbf{n}i})}{\mu_{\mathbf{n}}(\mathbf{A}_{\mathbf{n}i})} - \frac{\nu_{\mathbf{n}}(\mathbf{A}_{\mathbf{n}i})}{\mu(\mathbf{A}_{\mathbf{n}i})} \right| \cdot \mu(\mathbf{A}_{\mathbf{n}i}) \le 1$$

$$\leq K\mu_{\mathbf{n}}(\mathbf{A_{\mathbf{n}i}}) \left| \frac{1}{\mu_{\mathbf{n}}(\mathbf{A_{\mathbf{n}i}})} - \frac{1}{\mu(\mathbf{A_{\mathbf{n}i}})} \right| \mu(\mathbf{A_{\mathbf{n}i}}) =$$

$$= K | \mu_{n}(A_{ni}) - \mu(A_{ni}) |.$$
 (12)

If $\mu(A_{ni})>0$ and $\mu_n(A_{ni})=0$ then $\nu_n(A_{ni})=0$ therefore

$$\int_{\mathbf{A}_{\mathbf{n}i}} |\mathbf{m}_{\mathbf{n}}(\mathbf{x}) - \frac{\mathbf{v}_{\mathbf{n}}(\mathbf{A}_{\mathbf{n}i})}{\mu(\mathbf{A}_{\mathbf{n}i})}| \mu(\mathbf{d}\mathbf{x}) =$$

$$= \left| \frac{1}{n} \sum_{j=1}^{n} Y_{j} \right| \mu(A_{ni}) \leq K \left| \mu(A_{ni}) - \mu_{n}(A_{ni}) \right|$$
 (13)

_By (10), (11), (12) and (13) we have

$$f \mid \mathbf{m_n}(\mathbf{x}) - \mathbf{m}(\mathbf{x}) \mid \mu(\mathbf{dx}) \le 2K \mu(S^c) +$$

+
$$K \Sigma |\mu_n(A_{ni}) - \mu(A_{ni})| + \Sigma |\nu_n(A_{ni}) - \nu(A_{ni})'| + i \in I_{Sn}$$

$$+\sum_{\mathbf{i}\in \mathbf{I}_{Sn}} f \left| \frac{\nu(\mathbf{A}_{n\mathbf{i}})}{\mu(\mathbf{A}_{n\mathbf{i}})} - m(\mathbf{x}) \right| \mu \quad (d\mathbf{x})$$

By appropriate choice of S the first term can be arbitrary small, the fourth term tends to zero by Lemma 2. The expo-

nential bounds of the second and third terms result from condition (4) and from Lemma 1.

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